

Sec 7.4 Gallery of solutions

System $\underline{X}' = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \underline{X}$, general solutions $\underline{X} = c_1 \underline{X}_1 + c_2 \underline{X}_2$

Can classify how solution curves look/behave near origin.

Part I: Distinct real eigenvalues:

Say λ_1, λ_2 e-values, ($\lambda_1 \neq \lambda_2$)

$\underline{v}_1, \underline{v}_2$ e-vectors, lin indep

solution is $\underline{X} = c_1 \cdot \underline{e^{\lambda_1 t} \underline{v}_1} + c_2 \cdot \underline{e^{\lambda_2 t} \underline{v}_2}$

decays $\rightarrow 0$
if $\lambda_1 < 0$

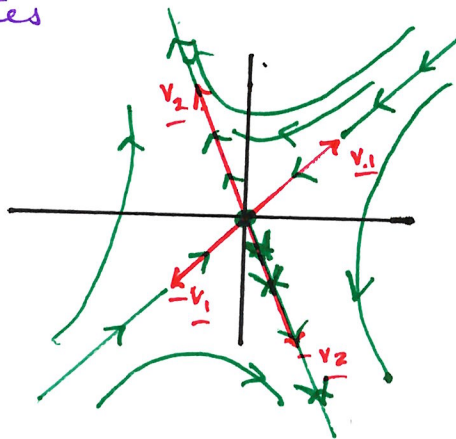
goes to ∞ if $\lambda_2 > 0$

Case 1: λ_1, λ_2 nonzero, opposite sign

Ex: $\lambda_1 < 0 < \lambda_2$

- pos./neg. eigenvalue accelerates curve away/to origin

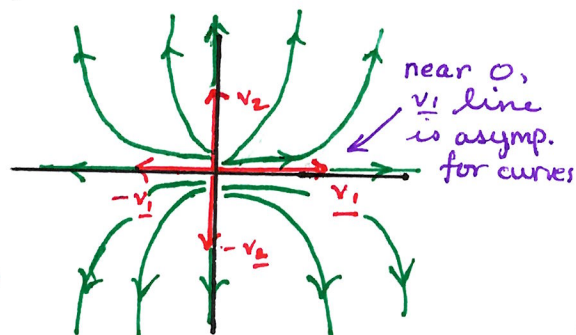
In this case, the origin is a saddle point.



Case 2: λ_1, λ_2 have same sign ($\neq 0$)

Ex: $0 < \lambda_1 < \lambda_2$

$c_1 \underline{e^{\lambda_1 t} \underline{v}_1} + c_2 \underline{e^{\lambda_2 t} \underline{v}_2}$
 $\lambda_1 < \lambda_2 \Rightarrow$ stronger influence $t \rightarrow -\infty$ $\lambda_2 > \lambda_1 \Rightarrow$ stronger push as $t \rightarrow \infty$



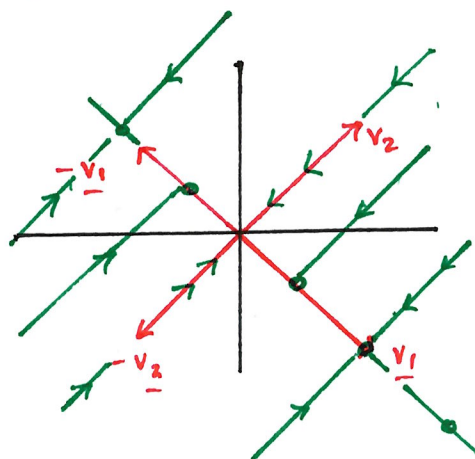
In this case, origin is an improper nodal source/sink.

(b/c the "accelerations" in diff. directions are unequal)

(source if curves go out
sink if curves come in)

Case One eigenval = 0 (say, ex: $\lambda_1 = 0$, $\lambda_2 = -3$)

no movement along $\underline{v}_1$ line
we get parallel lines



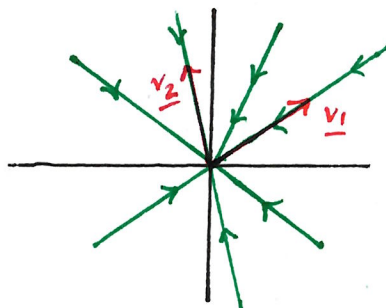
PART II : Repeated real eigenvalue:

Case: eigenvalue $\lambda \neq 0$ is repeated (has alg. mult. 2) and is complete (defect = 0) $\Rightarrow \underline{v}_1, \underline{v}_2$ are lin. indep. eigenvectors for λ . ("true eigenvectors")

Solution is $\underline{X} = c_1 e^{\lambda t} \underline{v}_1 + c_2 e^{\lambda t} \underline{v}_2 = e^{\lambda t} (c_1 \underline{v}_1 + c_2 \underline{v}_2)$

Ex: $\lambda = -1$, $\underline{v}_1, \underline{v}_2$ are basis for E_{-1} :

Here the origin is a proper nodal source/sink



Case $\lambda \neq 0$ repeated, but is defective (alg. mult. 2, only "defective option" is $\text{defect} = 2 - 1 = 1$.)

have $\underline{v}_1$ "true eigenvector"

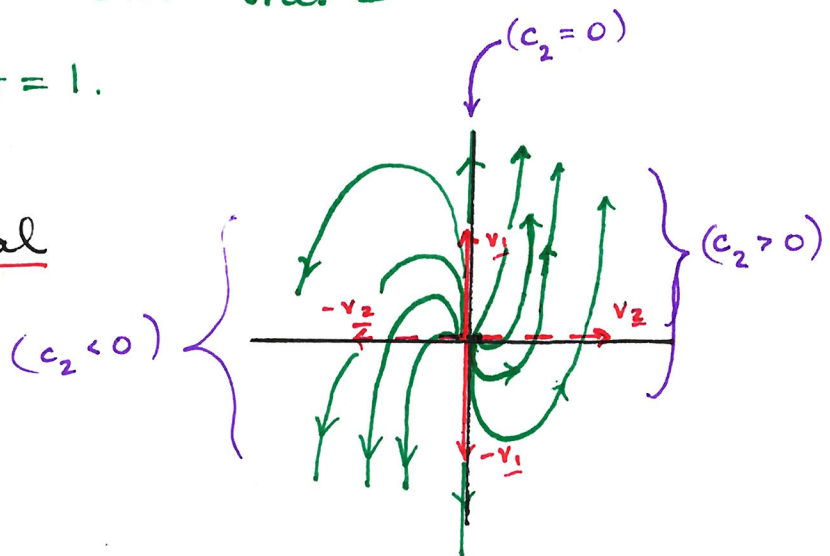
$\underline{v}_2$ "virtual eigenvector"

Solution is $\underline{X} = c_1 e^{\lambda t} \underline{v}_1 + c_2 e^{\lambda t} (t \underline{v}_1 + \underline{v}_2)$

$$= \underbrace{(c_1 + c_2 t) e^{\lambda t} \underline{v}_1}_{\text{eventually dominates over this}} + c_2 e^{\lambda t} \underline{v}_2$$

Ex: $\lambda > 0$, defect = 1.

Here, again origin is an improper nodal source/sink



★ Read other cases in section 7.4, and look at summary table there.

★ For complex eigenvalues, can't draw eigenvectors.